

CANPro Technical Manual

Table of Contents

CAN Commands

INTRODUCTION

[Use of this Document](#)

[Validity of this Document](#)

[Definitions and Abbreviations](#)

[Overview](#)

CAN Commands

STATE DIAGRAM AND PROGRAMS

General

INIT to STANDBY

Init

Table Load

Reset

Flash Load

Flash Read

Terminate and Safety Functions

Cancel Mode, Cancel Scan

Terminate by SJ

Information, Warning, Error and Abort

Stop

Halt

Lifecheck / Cancel IRS (P10 only)

Door and Cover Switches

Patient Positioning and Collision

ICT Mode (P20 only)

Automatic Tilt Depending Correction (P20 only)

Collision Test

Patient Positioning (horizontal, vertical and tilt)

Horizontal Position Zero

Light Marker

Key Disable, Enable and Highlight, API Lamp

Mode “Load” to Mode “Loaded”

Table Load and Call

The ‘Cycle’

Scan Load

Scan Execute

Scan Execute Premeasurement

Scan Execute Static

Scan Execute Rot Mode

Scan Execute Topogram

Scan Execute Spiral

CAN Commands

COMMANDS

General

List of Commands

Identifiers

[Groups of Identifiers](#)

[CAN Identifier List](#)

[CAN Register](#)

Who Am I - List

Description of Commands

[AD Abort Done](#)

[AS Abort Start](#)

[BA Break All Move](#)

[BH Break Horizontal Move](#)

[BT Break Tilt Move](#)

[BV Break Vertical Move](#)

[CH Cancel Horizontal Position](#)

[CM Cancel Mode](#)

[CS Cancel Scan](#)

[CT Cancel Tilt Position](#)

[CV Cancel Vertical Position](#)

[E# Error](#)

[FB Flash Block Number](#)

[FC Flash Clear](#)

[FD Flash Load Done](#)

[FR Flash Read](#)

[FS Flash Load Start](#)

[FV Flash Verify](#)

[GH Go Horizontal Move](#)

[GT Go Tilt Move](#)

[GV Go Vertical Move](#)

[HD Halt Done](#)

[ID Init Done](#)

[IR Init Request](#)

[IS Init Start](#)

[KA Key API Lamp](#)

[KD Keys Disable](#)

[KE Keys Enable](#)

[KH Keys Highlight](#)

[KN Keys Normal](#)

[LC Loaded Detector Comb \(P20 only\)](#)

[LD Loaded Detector Collimator \(P20 only\)](#)

[LF Loaded Filament](#)

[LR Loaded Rotation](#)

[LS Loaded Scan](#)

[LT Loaded Tube Collimator](#)

[MD Marker Done](#)

[MS Marker Start](#)

[PH Position Horizontal](#)

[PI Position ICT \(P20 only\)](#)

[PO Position Option \(P20 only\)](#)

[PT Position Tilt](#)

[PV Position Vertical](#)

[PZ Position Zero](#)

[QD Quality Service done](#)

[QS Quality Service Start](#)

[RD Reset Done](#)

[RS Reset Start](#)

[RW Reset Working](#)

[SE Start Execute](#)

[SF Start Footswitch](#)

[SJ Start Jump](#)

[SL Start Load](#)

[U# Table Query](#)

[V# Table Verified](#)

[XA Anode Executed](#)

[XF Filament Executed](#)

[XS Scan Executed](#)

[YD Lifecheck Done](#)

[YS Lifecheck Start](#)

[ZD Stop Done](#)

[ZT Stop from Tab Load](#)

CAN Commands

TABLES

TABLES

[General Format](#)

[TF0 Mode Table](#)

[Parameter](#)

[List of switches](#)

[Description of switches](#)

[Description of parameters](#)

[Limits of Mode Table parameters P10](#)

[Limits of Mode Table parameters P20](#)

[Calculation of Mode Table parameters](#)

[Modes](#)

[TF1 Cycle Table](#)

[TF2 Mode Table \(second\)](#)

[TF3 Cycle Table \(second\)](#)

CAN Commands

TIMING

[Project 10](#)

[Project 20](#)

CAN Tables

INTRODUCTION

[Use of this Document](#)

[Validity of this Document](#)

[Definitions and Abbreviations](#)

[Overview](#)

CAN Tables

TABLES

General

Tx0 to Tx9 Common Tables

Tx0 Status Tables

T00 : state MCU

T10 : state GPC

T20 : state RTC

T30 : state PTH

T40 : state PTV

T50 : state XRS

T90 : state DLP

TA0 : state ZCO

TB0 : state DOM

TC0 : state ACU

Tx1 Firmware Version (ID) Tables

Tx2 Receive History Buffer

Tx3 Transmit History Buffer

Tx4 Error Priority

Tx5 Debug Tables

Tx6 Timeout Tables

T06 : MCU Timeout Table

T16 : GPC Timeout Table

T26 : RTC Timeout Table

T36 : PTH Timeout Table

T46 : PTV Timeout Table

TA6 : ZCO Timeout Table

TC6: ACU Timeout Table

Tx7 Collision Parameters Set 1

Collision Parameters Drawing

T57 : XRS FIL Control Parameter Table

Tx8 Collision Parameters Set 2

Collision Parameters Drawing

T58 : XRS kV Control Parameter Table

TxA - TxF Application Tables

General and List

T0A - T0F : MCU Application Tables

T0A : WCS parameters

T0B : Configuration

T0C : Parameters for gantry climate control

T1A - T1F : GPC Application Tables

T1A : GPC Limit Values

T1B : GPC Slice Difference

T1C : GPC positioning speed and fine positioning

T2A - T2F : RTC Application Tables

T2A : RTC Machine Parameters

T2B : RTC AP Timing

T3A - T3F : PTH Application Tables

T3C : PTH Motion Controller Parameters

T3D : PTH Move Parameters

T4A - T4F : PTV Application Tables

T4C : PTV Frequency Converter Table

T5A - T5F : XRS Application Tables

T5A : XRS Init Table

T5B : XRS EPLD Readout

T5C : XRS Self Test Table

T5D : XRS Error Info table

T5E : XRS Scan Info

T9A - T9F : DLP Application Tables

T9A : DLP Init Table

T9B : DLP detector collimator parameters

T9C : Collimator Control

TAA - TAF : ZCO Application Tables

TAA : ZCO Machine Parameters

TAB : ZCO Z Monitor Position

TBA - TBF : DOM Application Tables

TBA : DOM Init table

TCA - TCF : ACU Application Tables

TCA : ACU scan info table

TCB :ACU counter info table

TCC : ACU reads RCOM registers

TCD : ACU Init parameter table

TCE : ACU writes RCOM register table

SAFETY

TESTABILITY

VERSION PLANNING

OPEN POINTS

MODES

FLOWCHARTS

STOP AND STOP REPORT CIRCUIT

TABLE OF REQUIREMENTS